

Advanced Digital Logic Design – EECS 303

<http://ziyang.eecs.northwestern.edu/eecs303/>

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Today's topics

- Technology mapping
 - Binate covering
 - Tree mapping
- Arithmetic circuits
 - Number systems
 - Adders

Outline

1. Technology mapping
2. Homework

Section outline

1. Technology mapping

Overview

Binate covering formulation

Tree covering formulation

Decomposition

Technology mapping

- We know how to minimize two-level and multi-level logic
- Generally expressed in terms of simple gates, e.g., NAND2s and NOTs
- Need to map to efficient implementation in target technology
- Target technology consists of a set of gates
- Each has area, power consumption, and timing properties
- Map to those gates minimizing some combination of area, power, and delay

Technology mapping

Given:

- Simplified and decomposed (reduced) logic graph (DAG)
 - Tree makes things easier
- Composed of *NOT* and *NAND2* gates
- Library: *NOT*, *NAND2*, *NAND3*, *ANDOR4 (AO4)*, and *XNOR* gates

Decide minimal area/delay/power cost mapping from logic tree to technology library

Technology mapping

Given:

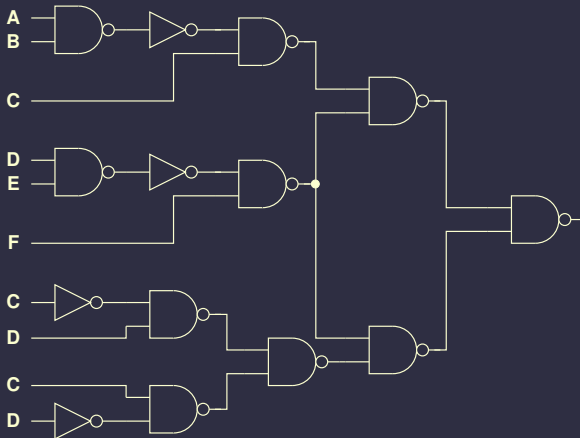
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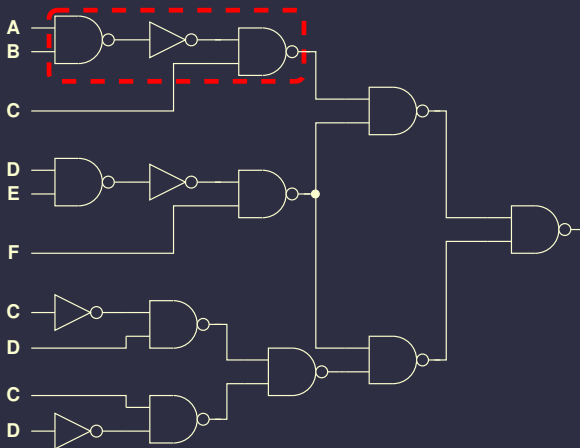
Technology mapping example library

| gate | area cost |
|--------|-----------|
| NOT | 1 |
| NAND2 | 2 |
| NAND3 | 3 |
| NAND4 | 4 |
| XNOR2 | 5 |
| ANDOR4 | 4 |

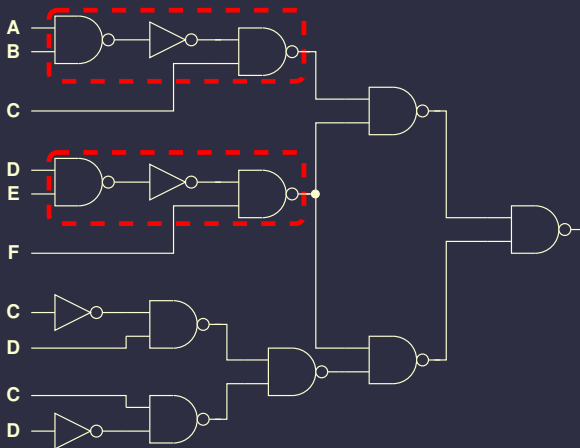
Potentially overlapping maps



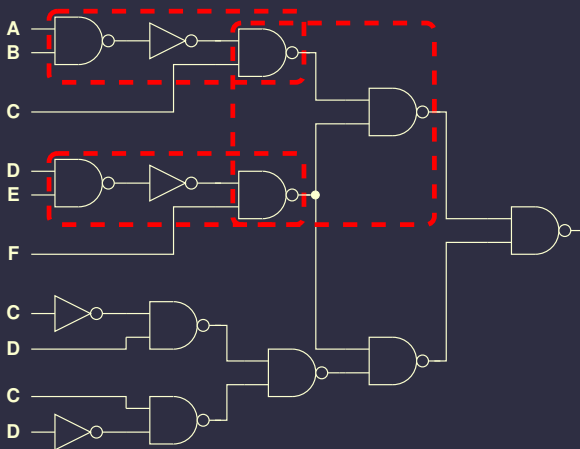
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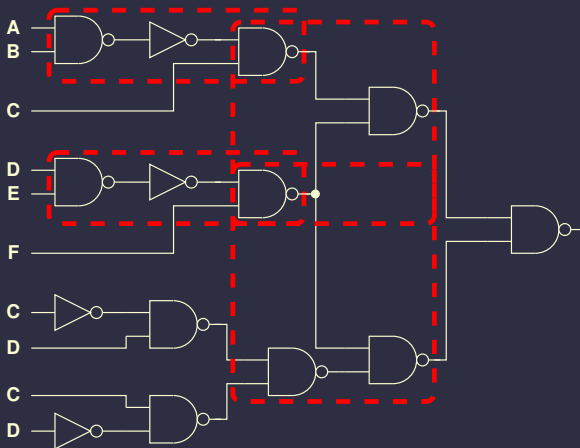
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Technology mapping for area as binate covering

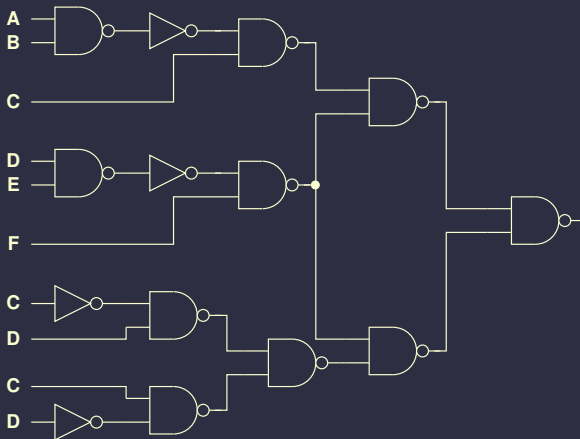
- Find all possible matches
- However, complete cover insufficient
 - Need match outputs to align with inputs of other matches
- Can represent problem as binate covering

Binate covering

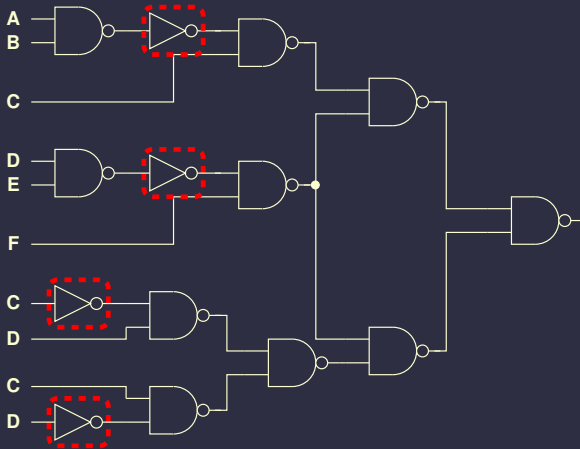
| term | column | | | |
|-------|--------|---|---|---|
| | A | B | C | D |
| J_1 | 1 | | | |
| J_2 | 1 | 1 | | |
| J_3 | | 1 | 1 | |
| J_4 | | | 1 | 1 |
| J_5 | 1 | | 0 | |

- Find a set of columns, S , such that, for every row
 - A 1-column in the row is in S or...
 - ...a 0-column in the row is not in S

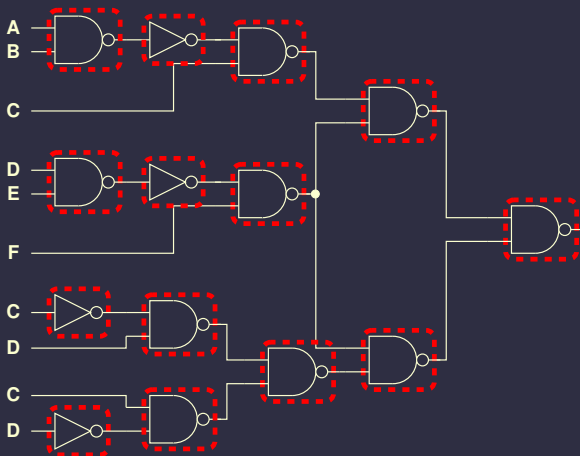
DAG mapping binate covering formulation



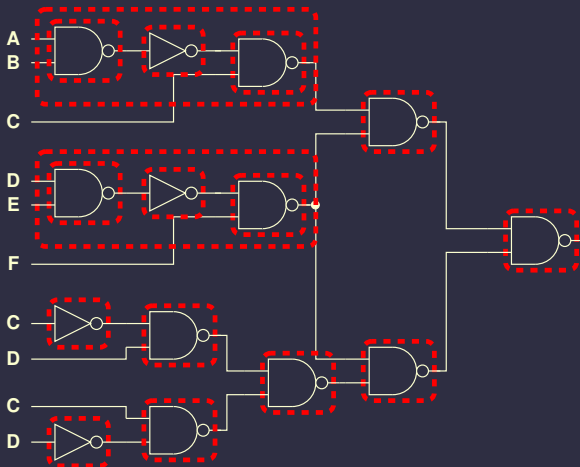
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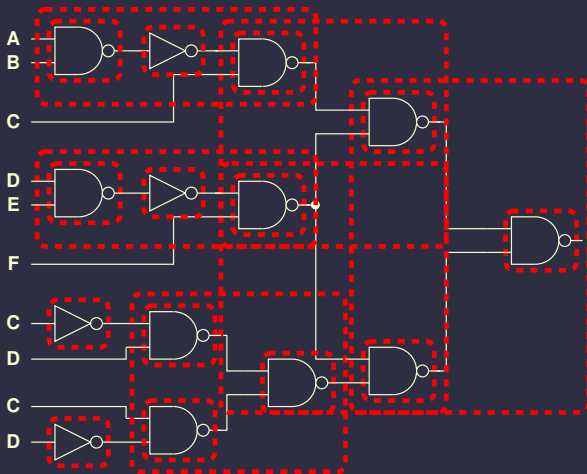
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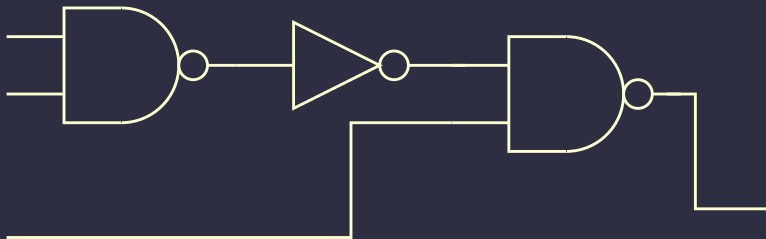
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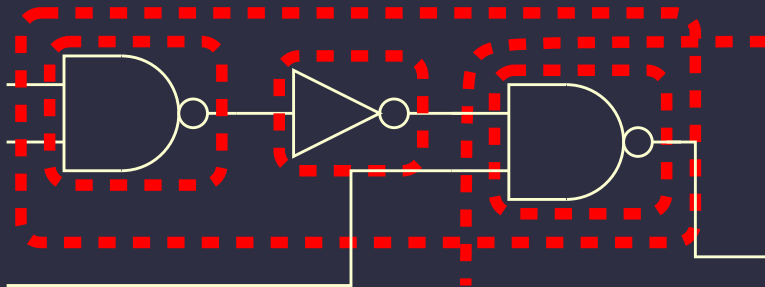


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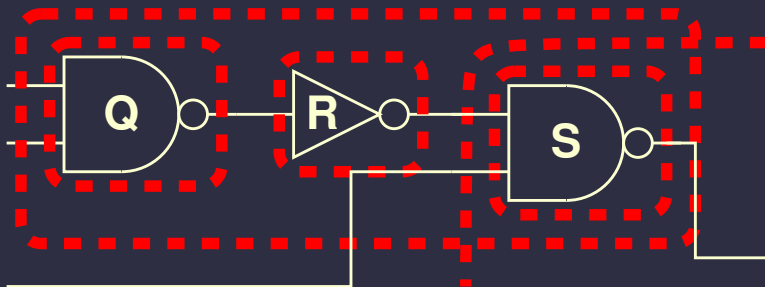
$$(\bar{J} \vee K) \wedge (\bar{K} \vee J) \wedge (\bar{K} \vee L \vee N) \wedge (\bar{L} \vee K) \wedge (\bar{N} \vee K)$$

DAG mapping binate covering formulation



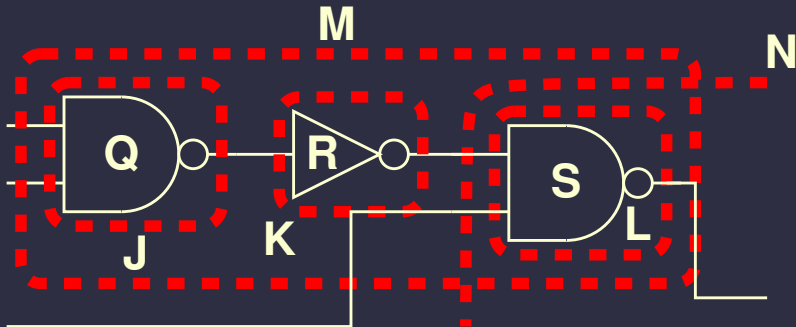
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DAG mapping binate covering formulation



$$(\bar{J} \vee K) \wedge (\bar{K} \vee J) \wedge (\bar{K} \vee L \vee N) \wedge (\bar{L} \vee K) \wedge (\bar{N} \vee K)$$

DAG mapping binate covering formulation

Outputs feed directly into next gate's inputs

$$(\bar{J} \vee K) \wedge (\bar{K} \vee J) \wedge (\bar{K} \vee L \vee N) \wedge (\bar{L} \vee K) \wedge (\bar{N} \vee K)$$

Also ensure primary outputs are available (omitted from example)

| constraint | gate | | | | |
|-------------------------|------|---|---|---|---|
| | J | K | L | M | N |
| Q | 1 | | | 1 | |
| R | | 1 | | 1 | |
| S | | | 1 | 1 | 1 |
| $\bar{J} \vee K$ | 0 | 1 | | | |
| $\bar{K} \vee J$ | 1 | 0 | | | |
| $\bar{K} \vee L \vee N$ | | 0 | 1 | | 1 |
| $\bar{L} \vee K$ | | 1 | 0 | | |
| $\bar{N} \vee K$ | | 1 | | | 0 |

Problems with binate covering

- Although there are good heuristics to speed up unate covering, binate covering appears to be a harder problem
 - Intractable for large problem instances
- Cost function must be independent of other portions of solution
 - Can use area but can't use delay or power
- Can use a fast alternative for tree, not DAG covering

Section outline

1. Technology mapping

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Binate covering formulation

Tree covering formulation

Decomposition

Tree covering

- Split DAG at multiple output nodes to form trees
- Optimally and quickly map trees using dynamic programming
- Reconnect result into a DAG
- Locally improve connection points
- Result: Nearly (but not quite) optimal, fast DAG mapping

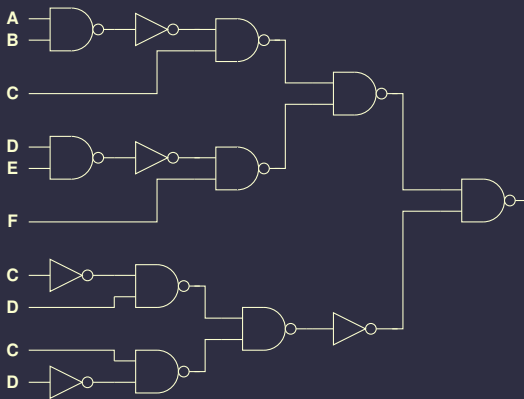
Technology mapping for area complexity

- Reduced logic tree $RLT = (V, E)$
- Technology library with T gates
- Maximum gate size of S , i.e., no gate covers more than S vertices

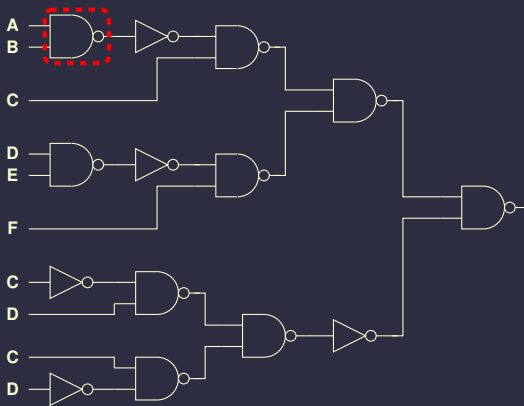
Algorithm is

- Linear in $|V|$
- Linear in T
- Exponential in S

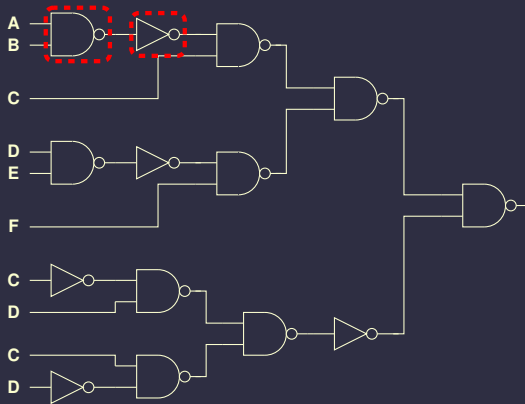
Tree technology mapping for area (detailed)



Tree technology mapping for area (detailed)

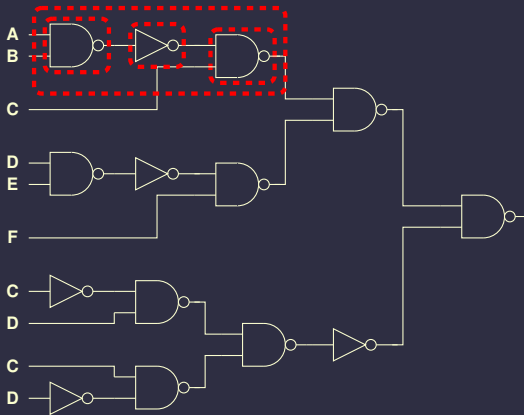


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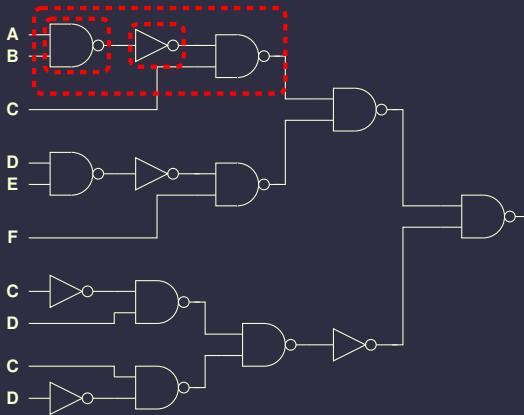
Tree technology mapping for area (detailed)

$$2 \cdot \text{NAND2}(2) + \text{NOT}(1) = 5 \text{ or } \text{NAND3}(3) = 3$$

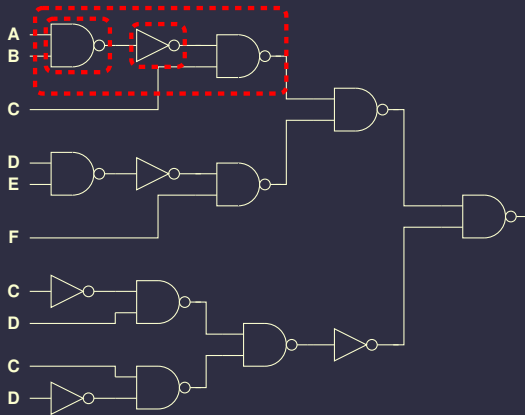


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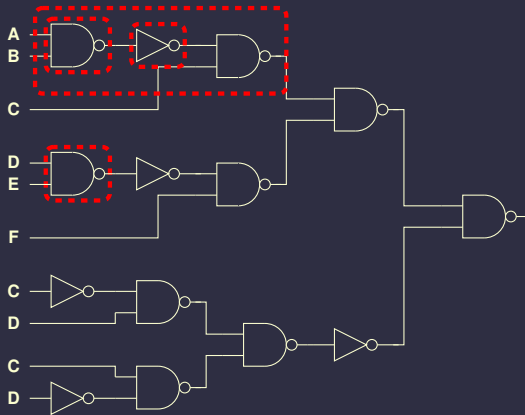
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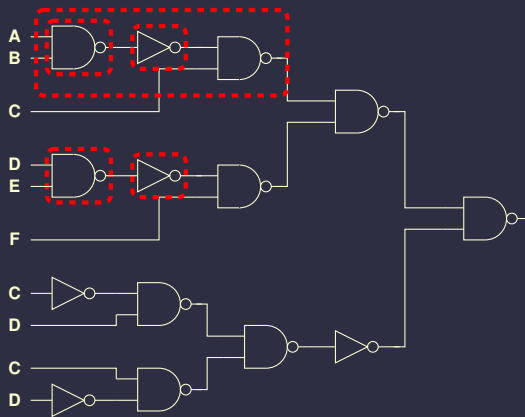
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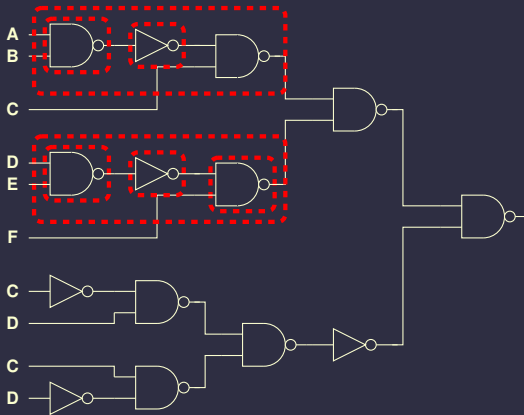
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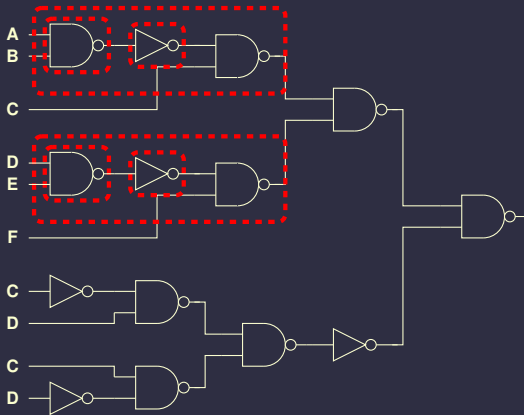
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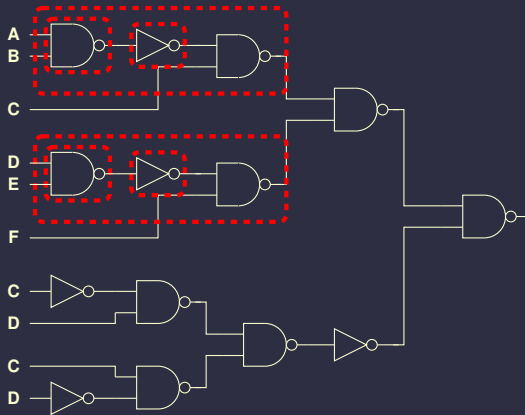
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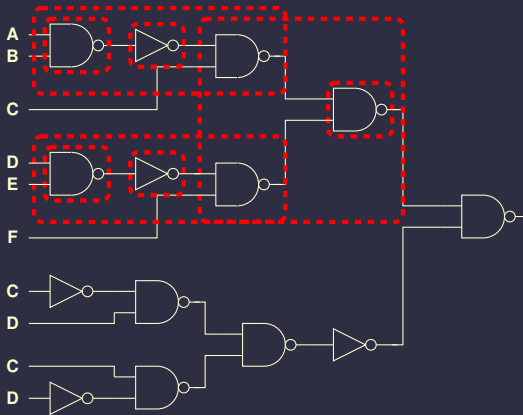


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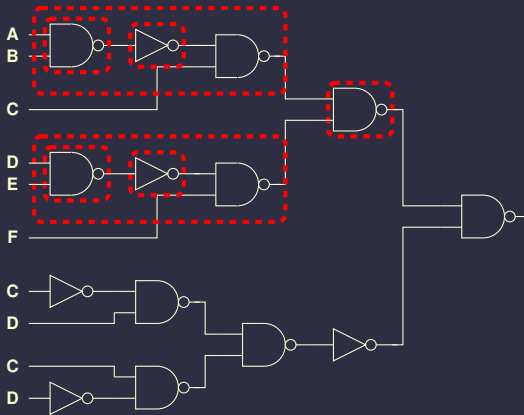
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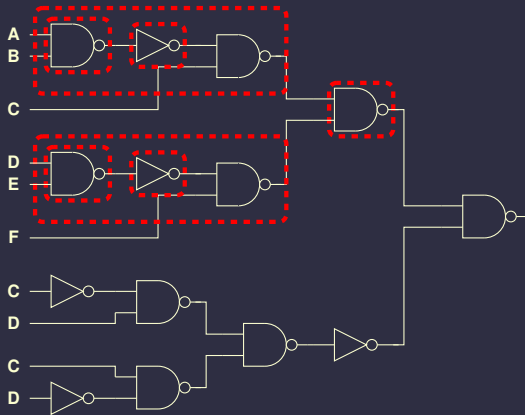


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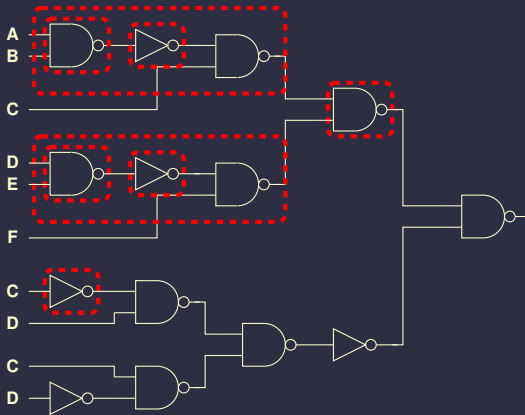
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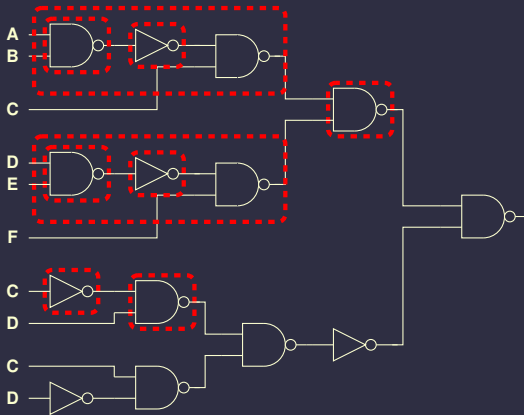
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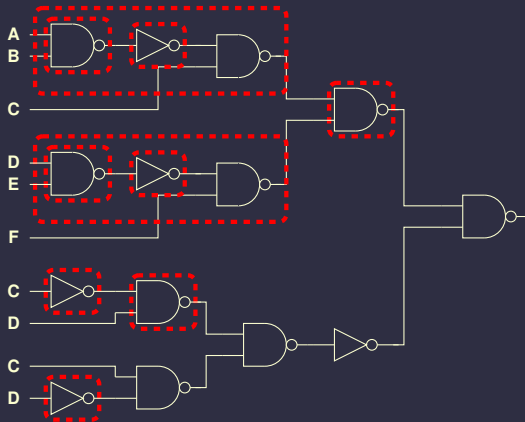
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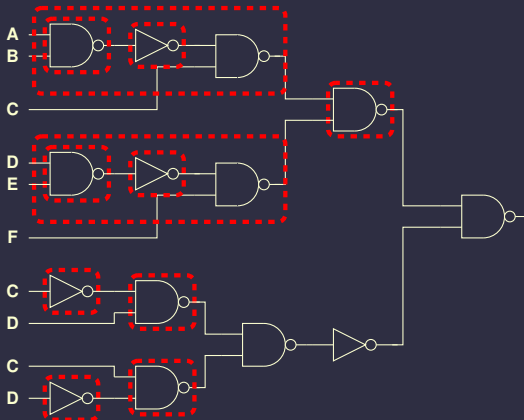
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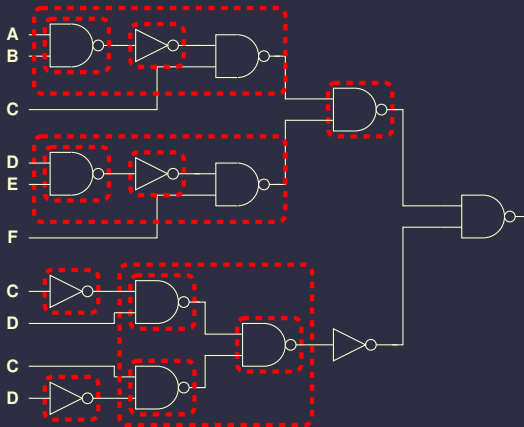


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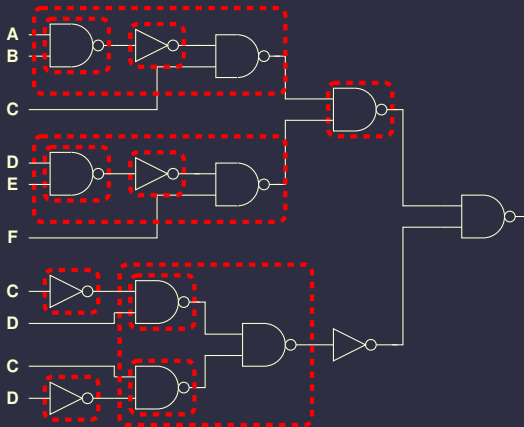
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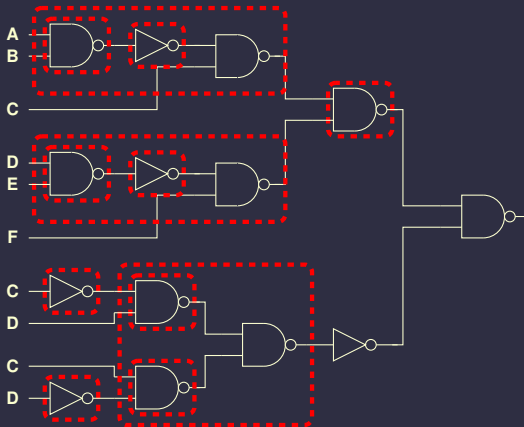


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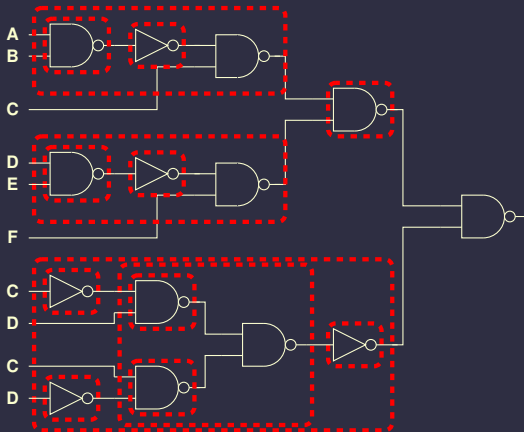


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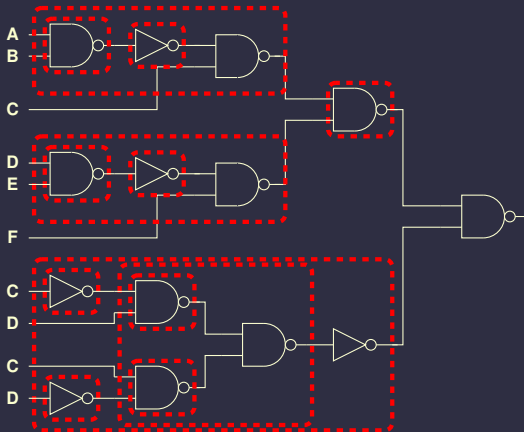
Tree technology mapping for area (detailed)

$$3 \cdot NOT(1) + ANDOR4(4) = 7 \text{ or } XNOR2(5) = 5$$

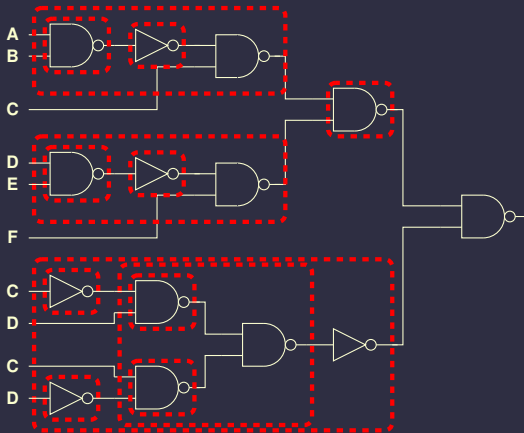


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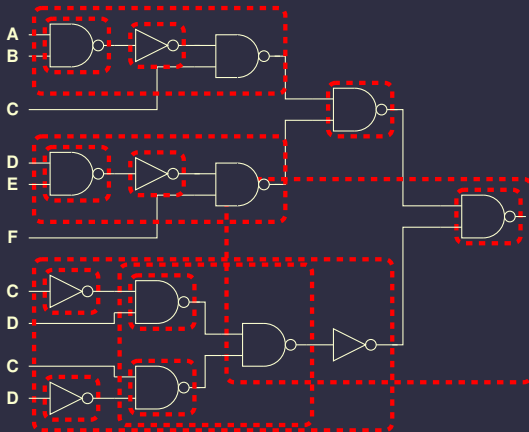


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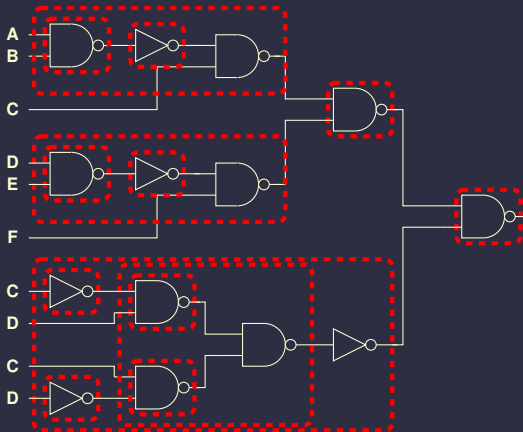
Tree technology mapping for area (detailed)

$$XNOR2(5) + NAND2(2) = 7 \text{ or } 2 \cdot NOT(1) + 2 \cdot NAND2(2) + NAND3(3) = 9$$

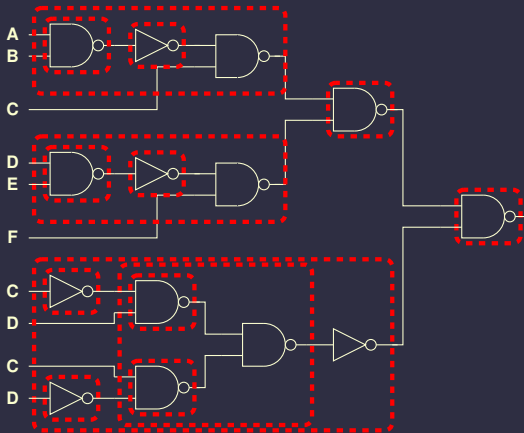


Tree technology mapping for area (detailed)

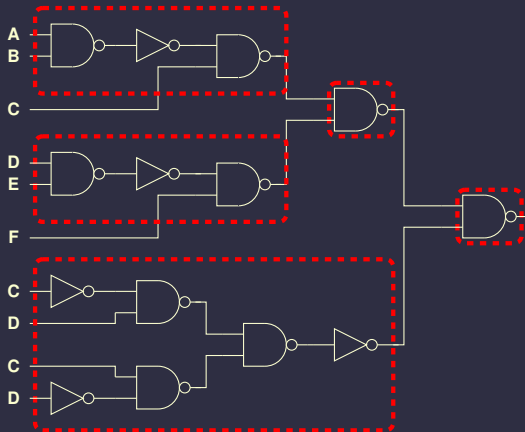
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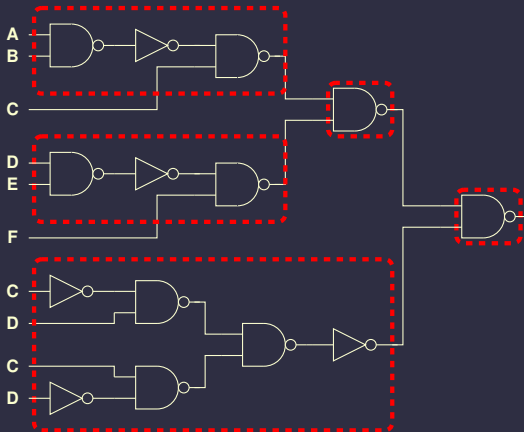


Tree technology mapping for area (detailed)



Tree technology mapping for area (detailed)

$$2 \cdot \text{NAND3}(3) + \text{XNOR2}(5) + 2 \cdot \text{NAND2}(2) = 15$$

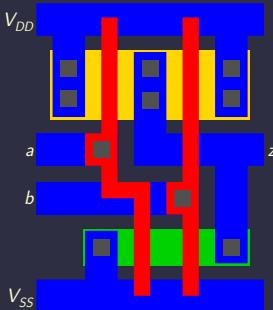


Technology mapping for speed

- If each gate had a different constant delay, could use simple dynamic programming algorithm
 - This works pretty well but is suboptimal
- However, each gate's speed depends on next gate's input load

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Two-pass delay optimization

Problem: Optimize area under timing constraint

- 1 Find the set of all possible pin-loads
- 2 From leafs, build array of minimal-area solutions, one for each pin-load
- 3 Calculate the arrival time for each possible mapping (pin-load)
- 4 For each point, select the optimal area solution for each pin-load
- 5 Propagate optimal solution backwards from output load
 - Note, that this isn't efficient given a large number of pin-loads
 - Discretize

Technology mapping

- Are circuits really trees?
- What happens when they are not?

Section outline

1. Technology mapping

Overview

Binate covering formulation

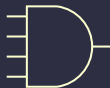
Tree covering formulation

Decomposition

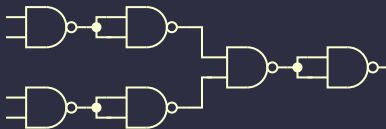
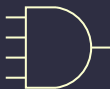
Decomposition for technology mapping

- Start from an arbitrary DAG of gates
- Want canonical DAG for technology mapping
 - E.g., NAND2 gates only
 - NAND2 with inputs tied is a NOT
- However, decomposition is not unique

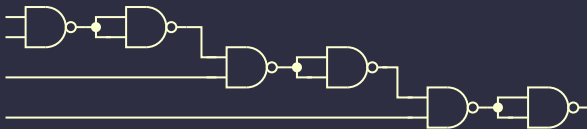
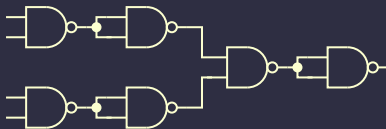
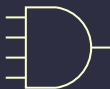
AND4 \rightarrow NAND2



AND4 \rightarrow NAND2



AND4 \rightarrow NAND2



Non-canonical decomposition

- Could decide to allow more complex gates in subject DAG
 - However, little opportunity for optimization
- Instead, consider all equivalent mappings for each library gate
- Can't consider numerous subject DAG
 - Complexity exponential
- Restated: Store many matches for each library gate but use only one subject DAG decomposition

Notes on optimality

- It is common for algorithm designers to come up with elegant and optimal algorithms
- Look closely at their assumptions!
- It is often, first, necessary to formulate a problem in a simplified form to arrive at an optimal solution
 - An optimal solution to the simplified form is not necessarily an optimal solution to the original problem

Notes on optimality

- The technology mapping algorithms in this lecture are polynomial-time (fast) and optimal. . .
- . . . however, they aren't polynomial-time (fast) in every term
 - Maximum library gate size
- . . . or optimal for the original problem
 - The original problem can be a DAG, instead of a tree
 - The decomposition is not unique
 - Better solutions might be possible for other decompositions

Notes on optimality

- The algorithms are high-quality and efficient
- However
 - They are only optimal with respect to the simplified inputs
 - They are only polynomial in the most important terms
- This situation is very common in EDA/CAD because the original problems are often \mathcal{NP} -complete
 - Too slow to solve for large problem instances
- Whenever you see or use the word “optimal”, think very carefully about what is meant

Technology mapping summary

- Technology mapping is taking a set of functions and determining how to implement them using gates from a library
- Optimal and fast approaches exist for trees
- However, no optimal solution is known for arbitrary circuit topologies
- This is what you are doing when you type “map” in SIS

Next lecture

- Multipliers and ALUs
- Sequential logic networks
- Latches (RS Latch)
- Flip-flops (D and JK)
- Timing issues (setup and hold times)

Outline

1. Technology mapping
2. Homework

Reading assignment

- M. Morris Mano and Charles R. Kime. *Logic and Computer Design Fundamentals*. Prentice-Hall, NJ, third edition, 2004
- Chapter 5